

Citation overview

Self citations of selected authors are excluded. ✕

[← Back to author details](#)

[↗ Export](#) [🖨 Print](#)

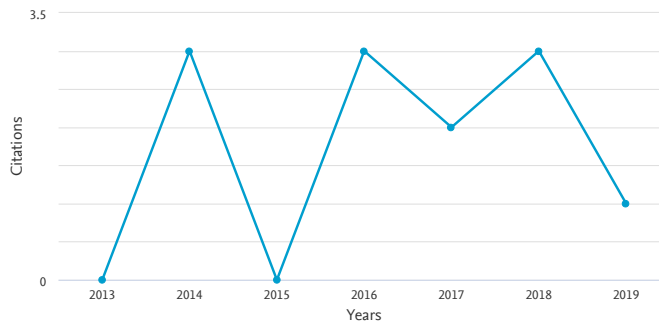
This is an overview of citations for this author.

Author *h*-index : 2 [View *h*-graph](#)

35 Cited Documents from "Sukop, Marek" [+ Add to list](#)

Author ID:36615762200

Date range: to Exclude self citations of selected author Exclude self citations of all authors Exclude citations from books Update



Sort on: Date (newest)

Page [🗑 Remove](#)

Documents	Citations										Subtotal	>2019	Total
		<2013	2013	2014	2015	2016	2017	2018	2019				
	Total	0	0	3	0	3	2	3	1	12	0	12	
<input type="checkbox"/> 1 MAS properties and classification	2019									0		0	
<input type="checkbox"/> 2 The methodology of creating overall strategy for well-develo...	2019									0		0	
<input type="checkbox"/> 3 The driver and its GUI (graphical user interface)	2019									0		0	
<input type="checkbox"/> 4 Multi-agent system test domain—robosoccer	2019									0		0	
<input type="checkbox"/> 5 Multi-agent system application in robosoccer	2019									0		0	
<input type="checkbox"/> 6 Multi-agent systems—terminology and definitions	2019									0		0	
<input type="checkbox"/> 7 Preface	2019									0		0	
<input type="checkbox"/> 8 Agent approach to multi-agent systems	2019									0		0	
<input type="checkbox"/> 9 Analysis of strategic behavior of mas depending on the basic...	2019									0		0	
<input type="checkbox"/> 10 Elementary agents players and their assignment to robots	2019									0		0	
<input type="checkbox"/> 11 Cognitive multi-agent systems: Structures, strategies and ap...	2019								1	1		1	
<input type="checkbox"/> 12 Hierarchical arrangement of the agents in developed MAS and ...	2019									0		0	
<input type="checkbox"/> 13 Robot vision ultra-wideband wireless sensor in non-cooperati...	2018										1	1	
<input type="checkbox"/> 14 Design of reconfigurable robot	2018									0		0	

Documents	Citations	<2013	2013	2014	2015	2016	2017	2018	2019	Subtotal	>2019	Total
	Total	0	0	3	0	3	2	3	1	12	0	12
<input type="checkbox"/> 15 Principles of formation of flexible manufacturing systems	2018									0		0
<input type="checkbox"/> 16 Modeling and control of two-link snake	2018									0		0
<input type="checkbox"/> 17 Comparison of the delta robot ABB IRB 360 properties after c...	2018									0		0
<input type="checkbox"/> 18 Conceptual design of a leg-wheel chassis for rescue operatio...	2017									0		0
<input type="checkbox"/> 19 Mutual comparison of developed actuators for robotic arms of...	2017									0		0
<input type="checkbox"/> 20 [Testing of adhesive spray painting with robot, Ispitivanje ...	2017									0		0
<input type="checkbox"/> 21 Testing of parameters of proposed robotic wrist based on the...	2016							1		1		1
<input type="checkbox"/> 22 Measurement of weight of objects without affecting the handl...	2016									0		0
<input type="checkbox"/> 23 Developing new behavior strategies of robot soccer team Sjf ...	2016									0		0
<input type="checkbox"/> 24 Strategic behavior of the group of mobile robots for robosoc...	2015					1	1			2		2
<input type="checkbox"/> 25 Transferring image processing algorithms on application with...	2015						1			1		1
<input type="checkbox"/> 26 Higher speed of data between computers and mobile robots bas...	2015									0		0
<input type="checkbox"/> 27 Modular approach for design of technology units with rotary ...	2014									0		0
<input type="checkbox"/> 28 Multi-Devices application with industrial robot	2014									0		0
<input type="checkbox"/> 29 Robot as a soccer player in multi-robotic application	2014									0		0
<input type="checkbox"/> 30 Implementation of two cameras to robotic cell for recognitio...	2013							1		1		1
<input type="checkbox"/> 31 Strategic decision-making of MASTER software agent in terms ...	2013									0		0
<input type="checkbox"/> 32 Multi-agent robotic system - Robotic soccer in category miro...	2012			1		1				2		2
<input type="checkbox"/> 33 Design of humanoid's lower limb model for walking	2012			1						1		1
<input type="checkbox"/> 34 Stuctural design of walking and mathematical model of humano...	2010									0		0
<input type="checkbox"/> 35 Multiagents system with dynamic box change for MiroSot	2009			1		1				2		2

Display: results per page

1

[^ Top of page](#)

About Scopus

[What is Scopus](#)
[Content coverage](#)
[Scopus blog](#)
[Scopus API](#)
[Privacy matters](#)

Language

[日本語に切り替える](#)
[切换到简体中文](#)
[切换到繁體中文](#)
[Русский язык](#)

Customer Service

[Help](#)
[Contact us](#)

ELSEVIER

[Terms and conditions](#) [Privacy policy](#)

Copyright © Elsevier B.V. All rights reserved. Scopus® is a registered trademark of Elsevier B.V.

We use cookies to help provide and enhance our service and tailor content. By continuing, you agree to the use of cookies.

RELX